Non-stationary Process Mixtures for Extreme Streamflow Forecasting in the Central US

Reetam Majumder

Joint work with Brian J. Reich

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NC STATE UNIVERSITY

Motivation



Figure 1: 0.99 quantiles of seasonal precipitation for each HCDN site. Source: NClimGrid.

- The Central US (CUS) is characterized by severe convective storms, and precipitation trends that could potentially influence flooding
- Extreme streamflow is a key indicator of flood risk
- The USGS Hydro Climatic Data Network (HCDN) provides streamflow data for watersheds which are minimally impacted by anthropogenic activity.



Figure 2: Sample 0.99 quantile of annual streamflow maxima from 1972–2021. Source: HCDN.

- HCDN data for the CUS: 55 watersheds across HUC-02 Regions 10L and 11
- Challenge: Expressive spatial extremes processes often have intractable likelihoods, making computation challenging.
- Goal: Develop a flexible and tractable spatial extremes model for climate-informed estimation of annual streamflow maxima.

Marginal distribution of streamflow maxima

Let the annual streamflow maxima for year *t* and site **s** following a generalized extreme value distribution:

 $Y_t(\mathbf{s}) \sim GEV\{\mu_t(\mathbf{s}), \sigma_t(\mathbf{s}), \xi_t(\mathbf{s})\},\$

whose cumulative distribution function (CDF) $F_{t,s}(y) := \mathbb{P}[Y_t(s) < y]$ is

$$\mathbb{P}[Y_{t}(\mathbf{s}) < y] = \exp\left\{-\left[1 + \xi_{t}(\mathbf{s})\left(\frac{\mathbf{y} - \mu_{t}(\mathbf{s})}{\sigma_{t}(\mathbf{s})}\right)\right]^{-1/\xi_{t}(\mathbf{s})}\right\}.$$
 (1)

The CDF is defined over the set $\{y : 1 + \xi_t(\mathbf{s})(y - \mu_t(\mathbf{s})) / \sigma_t(\mathbf{s}) > 0\}$

Let Z_{1t} and Z_{2t} be the annual precipitation for the two HUC-02 regions (10L and 11); define $X_{1t}(s)$ as:

$$X_{1t}(\mathbf{s}) = \mathbb{I}\{\mathbf{s} \in \text{Region 10L}\}Z_{1t} + \mathbb{I}\{\mathbf{s} \in \text{Region 11}\}Z_{2t}$$

Denote $X_{it}(\mathbf{s}), i = 2, ..., 5$ as the seasonal precipitation for site \mathbf{s} for year t. GEV parameters vary spatially and depend on precipitation:

$$\mu_t(\mathbf{s}) = \mu_0(\mathbf{s}) + \sum_{i=1}^5 \mu_i(\mathbf{s}) \chi_{it}(\mathbf{s}), \qquad \sigma_t(\mathbf{s}) = \sigma(\mathbf{s}), \qquad \xi_t(\mathbf{s}) = \xi(\mathbf{s}).$$
(2)

Given streamflow data ($y_{1:n}$), marginal parameters (θ_1), and spatial process parameters (θ_2), our Bayesian hierarchical model is:

Prior model:
$$\theta_1 \sim p(\theta_1) \perp \theta_2 \sim p(\theta_2)$$
,
Data model: $f_y(y_1, ..., y_n | \theta_1, \theta_2) = \underbrace{f_u(u_1, ..., u_n | \theta_2)}_{\text{spatial dependence}} \underbrace{\prod_{i=1}^n \left| \frac{dF(y_i | \theta_1)}{dy_i} \right|}_{\text{marginal GFV likelihoods}}$

The CDF transformed variables $U_t(\mathbf{s}) := F_{t,\mathbf{s}}(Y_t(\mathbf{s}))$ share common uniform marginal distributions but are spatially correlated

This change-of-variables in the likelihood separates residual spatial dependence in $U_t(s)$ from spatial dependence induced by spatial variation in the GEV parameters.

The latter is modeled using Gaussian process priors on the components of $oldsymbol{ heta}_1$

A spatial dependence model on $U_t(\mathbf{s})$ is obtained via the transformation $U_t(\mathbf{s}) = G_{t,\mathbf{s}}(V_t(\mathbf{s}))$:

$$\mathcal{W}_{t}(\mathbf{s}) = \delta_{t}(\mathbf{s})R_{t}(\mathbf{s}) + (1 - \delta_{t}(\mathbf{s}))W_{t}(\mathbf{s}), \tag{3}$$

where $R_t(\mathbf{s})$ is a max-stable process, $W_t(\mathbf{s})$ is a Gaussian process. We call this a process mixture model

 $\delta_t(\mathbf{s}) \in [0, 1]$ are weight parameters depending on regional annual precipitation,

$$\delta_t(\mathbf{s}) = \mathbb{I}\{\mathbf{s} \in \text{Region 10L}\}\delta_{1t} + \mathbb{I}\{\mathbf{s} \in \text{Region 11}\}\delta_{2t}$$
(4)

$$g^{-1}(\delta_{it}) = \beta_{i0} + \beta_{i1} Z_{it}, i = 1, 2.$$
(5)

Dependence of $\delta_t(\mathbf{s})$ on precipitation introduces non-stationarity¹

If $\delta_t(\mathbf{s}) = \delta$, the NPMM simplifies to a stationary PMM²

¹Majumder and Reich (2023), Spat. Stat.

²Majumder, Reich, and Shaby (2022), *arXiv:2208.03344*. Huser and Wadsworth (2019), *J. Am. Stat. Assoc.*

Extremal spatial dependence often measured in terms of the upper-tail coefficient:

$$\chi_u(\mathbf{s}_1, \mathbf{s}_2) := \operatorname{Prob}\{U(\mathbf{s}_1) > u | U(\mathbf{s}_2) > u\},\tag{6}$$

where $u \in (0,1)$ is a threshold. $U(s_1)$ and $U(s_2)$ are defined to be asymptotically dependent if

$$\chi(\mathbf{s}_1, \mathbf{s}_2) = \lim_{u \to 1} \chi_u(\mathbf{s}_1, \mathbf{s}_2) \tag{7}$$

is positive, and independent if $\chi(\mathbf{s}_1, \mathbf{s}_2) = 0$. For the PMM/NPMM,

 $\delta < 0.5 \implies$ asymptotic independence, and

 $\delta > 0.5 \implies$ asymptotic dependence

Inference involves a Vecchia approximated density regression (VADeR) approach for the intractable joint likelihood

1. Use a Vecchia approximation³ to approximate the joint likelihood as:

$$f_{u}(u_{1},...,u_{n}|\boldsymbol{\theta}_{2}) = \prod_{i=1}^{n} f_{i}(u_{i}|\boldsymbol{\theta}_{2},u_{1},...,u_{i-1}) \approx \prod_{i=1}^{n} f_{i}(u_{i}|\boldsymbol{\theta}_{2},u_{(i)}), \quad (8)$$

 $u_{(i)} \subseteq \{u_1, \ldots, u_{i-1}\}$. The subset of locations $\mathbf{s}_{(i)}$ are often the nearest neighbors

- 2. Obtain density estimates of each term $f_i(u_i|\theta_2, u_{(i)})$ using a semi-parametric quantile regression (SPQR) model⁴
- 3. Use the surrogate likelihood in a Bayesian framework to obtain posterior estimates of $\pmb{\theta}_1$ and $\pmb{\theta}_2$

³Vecchia (1988), J. R. Stat. Soc. B. Stein, Chi, and Welty (2004), J. R. Stat. Soc. B.

⁴Xu and Reich (2021), Biometrics

Posterior of spatial process parameters for extreme streamflow

Precipitation and streamflow for HUC-02 regions 10L and 11 from 1972–2021:

Left: Time series of annual NClimGrid precipitation (in mm)

Right: Posterior means of δ_{1t} and δ_{2t} corresponding to regions 10L and 11



 δ_{1t} and δ_{2t} do not change with changes in basin-wide annual precipitation δ_{1t}, δ_{2t} have posterior means of 0.53 and 0.71 for the 50 year period (asymptotically dependent)

Posterior of GEV distribution parameters for extreme streamflow

- · Precipitation is a significant predictor of streamflow maxima
- Spring (AMJ) precipitation is the most significant predictor at most locations.



Figure 3: Estimates of $\mu(s) = \max(\mu_j(s))$ for j = 2 : 5 corresponding to the 4 seasons with shapes denoting the season with the highest slope value (left), and number of seasons (excluding annual) where $\mathbb{P}[\mu(s) > 0] > 0.90$ (right).

Scale and shape parameters estimates also show spatial variation Posterior mean of shape parameter is positive at 54 out of 55 locations



We use bias-corrected climate model precipitation output from CMIP5⁵ as covariates in the posterior predictive distribution of streamflow maxima to get projections for 2006–2035

6 CMIP5 models (3 wet + 3 dry) considered for each representative climate pathway (RCP) scenario, viz. RCP 4.5 and RCP 8.5

⁵Taylor, Stouffer, and Meehl (2012), B. Am. Meteorol. Soc.

Streamflow projections for the CUS



Figure 4: Percentage change in observed 0.90 quantile under RCP 4.5. Triangles denote an increase while circles denote a decrease.

We compare annual streamflow maxima for 2006–2035 against 1972–2005 Changes from -10.3% to 12.3% for the 0.90 quantile of annual streamflow maxima

Streamflow projections for the CUS



Figure 5: Percentage change in observed 0.90 quantile under RCP 8.5. Triangles denote an increase while circles denote a decrease.

All 6 models under RCP 4.5 and 4 models under RCP 8.5 estimate that more than 50% locations have increased streamflow in the projection period.

Less pronounced but similar results for the 0.99 quantile

- Significance: Precipitation is estimated to be a significant predictor of extremal streamflow in the CUS and shows a strong seasonal component
- Non-stationarity: The asymptotic dependence properties of the two HUC-02 regions are estimated to be different from each other, and each show inter-annual variability
- · Projections: Annual streamflow maxima is projected to increase in the near future
- Methodology: The NPMM is flexible (desirable asymptotic properties), and tractable (computational cost increases linearly in number of locations). The density estimation approach can be used for any intractable spatial process
- Brian's talk (Tuesday afternoon) will go into more details of the methodology

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Vecchia approximation of intractable likelihood



Problem: Evaluate the NPMM likelihood for any values of θ_2 and (y_1, \ldots, y_n)

Approach: Density estimation of surrogate univariate conditional likelihoods based on a Vecchia decomposition of the joint distribution $f_u(u_1, ..., u_n | \theta_2)$:

$$f_{u}(u_{1},...,u_{n}|\boldsymbol{\theta}_{2}) = \prod_{i=1}^{n} f_{i}(u_{i}|\boldsymbol{\theta}_{2},u_{1},...,u_{i-1}) \approx \prod_{i=1}^{n} f_{i}(u_{i}|\boldsymbol{\theta}_{2},u_{(i)}),$$
(9)

 $u_{(i)} \subseteq \{u_1, \dots, u_{i-1}\}$. The subset of locations $\mathbf{s}_{(i)}$ are often the nearest neighbors.

Density regression is carried out for each of the n - 1 terms separately using neural networks in a semi-parametric quantile regression (SPQR) model⁶:

$$f_i(u_i|\mathbf{x}_i, \mathcal{W}) = \sum_{k=1}^{K} \pi_{ik}(\mathbf{x}_i, \mathcal{W}_i) B_k(u_i),$$
(10)

$$\pi_{ik}(\mathbf{x}_i, \mathcal{W}_i) = f_i^{NN}(\mathbf{x}_i, \mathcal{W}_i), \text{ for } i = 2, \dots, n.$$
(11)

- $\mathbf{x}_i = (u_{(i)}, \boldsymbol{\theta}_2)$ are treated as covariates, with u_i as the response variable
- Each NN maximizes the log-likelihood of a univariate conditional (RHS of (10))
- NNs are trained using synthetic data (surrogate likelihood)
- Given a value of θ_2 and $u_{(i)} = F(y_{(i)})$, we can then evaluate $f_u(u_1, ..., u_n | \theta_2)$ as a product of surrogate conditional distributions
- Can be used in an MCMC to estimate θ_1 and θ_2 .

⁶Xu and Reich (2021), Biometrics.